

Coordinates

a guest lecture by

Kent

University of Waterloo
j346huan@uwaterloo.com

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Last time

Given a vector $\vec{a} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = \underline{a_1 \vec{e}_1} + \cdots + \underline{a_n \vec{e}_n}$, the numbers a_1, \dots, a_n are its **coordinates**, and if you form a vector with these numbers, you get

$$[\vec{a}]_{\mathcal{B}_{\text{std}}} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}.$$

...

BUT these numbers are obtained by expressing \vec{a} using the standard basis $\mathcal{B}_{\text{std}} = \{\vec{e}_1, \dots, \vec{e}_n\}$. So everything above is **relative to \mathcal{B}_{std}** .

If you use a different basis $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_n\}$, as opposed to the standard basis, you can express \vec{v} differently, say

$$\vec{a} = \underline{b_1 \vec{v}_1} + \dots + b_n \vec{v}_n.$$

The **coordinates with respect to \mathcal{B}** are the values b_1, \dots, b_n , and they form the **coordinate vector of \vec{v} with respect to \mathcal{B}**

$$[\vec{v}]_{\mathcal{B}} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

Example

$$\mathbb{S} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid x_1 + 2x_2 - x_3 = 0 \right\} \text{ with basis } \mathcal{B} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

What are the coordinates, with respect to \mathcal{B} , of the vector

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}?$$

Does not make sense
because $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \notin \mathbb{S}$.

Warning

It only makes sense to talk about the coordinate of a vector \vec{a} with respect to a basis \mathcal{B} , if $\vec{a} \in \text{Span}\mathcal{B}$.

Example

$$\mathbb{S} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid x_1 + 2x_2 - x_3 = 0 \right\} \text{ with basis } \mathcal{B} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Suppose $\vec{a} = \begin{bmatrix} -5 \\ 4 \\ 3 \end{bmatrix}$.

This time $\vec{a} \in \text{Span}\mathcal{B}$, so it makes sense to talk about its coordinates with respect to \mathcal{B} .

Get vector from coordinates

Say we are given a vector \vec{a} and a basis \mathcal{B} . How do we find $[\vec{a}]_{\mathcal{B}}$?

Example

$$\mathbb{S} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid x_1 + 2x_2 - x_3 = 0 \right\} \text{ with basis } \mathcal{B} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Suppose $\vec{a} = \begin{bmatrix} -5 \\ 4 \\ 3 \end{bmatrix}$. We need to express \vec{a} in terms of the vectors in

\mathcal{B} . So we need to find numbers b_1, b_2 such that

$$b_1 \cdot \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + b_2 \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \vec{a} = \begin{bmatrix} -5 \\ 4 \\ 3 \end{bmatrix}$$

Get vector from coordinates

Example (continued)

This is solved by row reducing the system:

$$\left[\begin{array}{cc|c} -2 & 1 & -5 \\ 1 & 0 & 4 \\ 0 & 1 & 3 \end{array} \right]$$

$$b_1 = 4$$

$$b_2 = 3$$

$$\sim \left[\begin{array}{cc|c} 1 & 0 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right]$$

$$[\vec{a}]_B = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

Remark

In the last example, \mathcal{B} is a basis of size 2 for the subspace $\mathbb{S} \subseteq \mathbb{R}^3$, so the dimension of \mathbb{S} is 2, and \mathcal{B} coordinate will consist of 2 numbers.

If $\mathbb{S} \subseteq \mathbb{R}^n$ has dimension k , and \mathcal{B} is a basis for \mathbb{S} , then for any $\vec{a} \in \mathbb{S}$, the \mathcal{B} -coordinate vector

$$[\vec{a}]_{\mathcal{B}}$$

has k numbers in it.

In application, the total space might be \mathbb{R}^{100} , but if we work in a subspace \mathbb{S} of small dimension, then using coordinates within \mathbb{S} will simplify computation.

Example (One more example)

$$\mathbb{S} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid x_3 = 0 \right\} \text{ with basis } \mathcal{B} = \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}.$$

Suppose $\vec{a} = \begin{bmatrix} -5 \\ 4 \\ 0 \end{bmatrix}$. Then

$$\vec{a} = 4 \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + (-5) \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

and

$$[\vec{a}]_{\mathcal{B}} = \begin{bmatrix} 4 \\ -5 \end{bmatrix}$$

Get vector from coordinates

Going in the reverse direction, if we are given $[\vec{a}]_{\mathcal{B}}$?

Example

$$\mathbb{S} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid x_1 + 2x_2 - x_3 = 0 \right\} \text{ with basis } \mathcal{B} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Suppose $[\vec{a}]_{\mathcal{B}} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$. Since \mathcal{B} has two elements, it make sense that a \mathcal{B} -coordinate vector has 2 numbers in it. Then

$$\vec{a} = 2 \cdot \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + 4 \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix}$$

Change of coordinates

If I have two bases \mathcal{B} and \mathcal{C} , and I know $[\vec{a}]_{\mathcal{B}}$, how do I find $[\vec{a}]_{\mathcal{C}}$?

Answer

You could compute \vec{a} first using $[\vec{a}]_{\mathcal{B}}$, then compute $[\vec{a}]_{\mathcal{C}}$.

OR, you could just use the **change of coordinates matrix**.

Definition (Definition 5.2.13)

Let $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_k\}$ and \mathcal{C} be two bases for a subspace \mathbb{S} of \mathbb{R}^n . The **change of coordinate matrix** from \mathcal{B} -coordinates to \mathcal{C} -coordinates is

$${}_C P_B = [[\vec{v}_1]_{\mathcal{C}} \quad [\vec{v}_2]_{\mathcal{C}} \quad \dots \quad [\vec{v}_k]_{\mathcal{C}}] \in M_{k \times k}(\mathbb{R})$$

Then for any $\vec{a} \in \mathbb{S}$ we have

$$[\vec{a}]_{\mathcal{C}} = {}_C P_B [\vec{a}]_{\mathcal{B}}.$$

Remark

Here \mathcal{C} is on the left, \mathcal{B} is on the right because it eats a \mathcal{B} coordinates on its right, and spits out a \mathcal{C} coordinates.

How do I find change of coordinates matrix from \mathcal{B} to \mathcal{C} ?

Answer

The definition says

$${}_C P_B = [[\vec{v}_1]_C \quad [\vec{v}_2]_C \quad \dots \quad [\vec{v}_k]_C].$$

You know how to compute each $[\vec{v}_i]_C$ individually, so you know how to compute the whole matrix.

OR, you could compute them all at once.

Example

$$\mathbb{S} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid x_1 + 2x_2 - x_3 = 0 \right\} \text{ with bases}$$

 $\mathcal{C}, \mathcal{P}_B$

$$\mathcal{B} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}, \mathcal{C} = \left\{ \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -5 \\ 4 \\ 3 \end{bmatrix} \right\}$$

To find $\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}_{\mathcal{C}}$ and $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}_{\mathcal{C}}$, we need to row reduce

$$\left[\begin{array}{cc|c|c} -1 & -5 & -2 & 1 \\ 1 & 4 & 1 & 0 \\ 1 & 3 & 0 & 0 \end{array} \right]$$

AND

$$\left[\begin{array}{cc|c|c} -1 & -5 & 1 & 1 \\ 1 & 4 & 0 & 0 \\ 1 & 3 & 1 & 1 \end{array} \right]$$

Example

But we could instead just row reduce

$$\left[\begin{array}{cc|cc} -1 & -5 & -2 & 1 \\ 1 & 4 & 1 & 0 \\ 1 & 3 & 0 & 1 \end{array} \right]$$

$$cP_B = \begin{bmatrix} -3 & 4 \\ 1 & -1 \end{bmatrix}$$

$$\sim \left[\begin{array}{cc|cc} 0 & -1 & -1 & 1 \\ 1 & 4 & 1 & 0 \\ 0 & -1 & -1 & 1 \end{array} \right]$$

$$\sim \left[\begin{array}{cc|cc} 1 & 0 & -3 & 4 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Example

$S = \mathbb{R}^3$ with bases

$$\underline{\mathcal{B}} = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ -3 \end{bmatrix} \right\}, \mathcal{B}_{\text{std}} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

To find $\mathcal{B}_{\text{std}} P_{\underline{\mathcal{B}}}$, we need to row reduce

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & -2 \\ 0 & 1 & 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 3 & 1 & 3 \end{array} \right]$$

$$\underline{\mathcal{B}_{\text{std}}} P_{\underline{\mathcal{B}}} = \begin{bmatrix} 1 & 1 & -2 \\ 2 & 0 & 0 \\ 3 & 1 & -3 \end{bmatrix}$$

Example

To find ${}_B P_{B_{\text{std}}}$, we need to row reduce

$$\left[\begin{array}{ccc|ccc} 1 & 1 & -2 & 1 & 0 & 0 \\ 2 & 0 & 0 & 0 & 1 & 0 \\ 3 & 1 & 3 & 0 & 0 & 1 \end{array} \right]$$

But this is just the process to find...

$${}_B P_{B_{\text{std}}} = \begin{bmatrix} 1 & 1 & -2 \\ 2 & 0 & 0 \\ 3 & 1 & 3 \end{bmatrix}^{-1} = {}_{B_{\text{std}}} P_B^{-1}$$

An important property

If I change the coordinates from a \mathcal{B} -coordinates to a \mathcal{C} -coordinates, then change it back, I would just retrieve the original coordinates. Therefore applying the change of coordinates matrix ${}_{\mathcal{C}}P_{\mathcal{B}}$, then ${}_{\mathcal{B}}P_{\mathcal{C}}$, does nothing.

Theorem

If \mathcal{B} and \mathcal{C} are bases for a subspace \mathbb{S} , then

$${}_{\mathcal{B}}P_{\mathcal{C}} {}_{\mathcal{C}}P_{\mathcal{B}} = I = {}_{\mathcal{C}}P_{\mathcal{B}} {}_{\mathcal{B}}P_{\mathcal{C}}$$

Next time

New chapter: Chapter 6 - Eigenvectors and Diagonalization

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