

Deformations of complex and Kähler structures

Defn A Calabi-Yau manifold is a compact Kähler manifold X with $\omega_X \cong \Omega_X$.

Sometimes there will be assumptions $H^i(\Omega_X) = 0$ for $i=1, i=1, 2, 3$ or just $i > 0$.

In deformation theory of moduli spaces, these conditions can simplify calculations.

When X is toric $H^i(\Omega_X) = 0 \quad \forall i > 0$. also get nice identities by some duality.

Complex structures

X cpt \mathbb{C} -mfld. Consider \mathbb{C} -str on X compatible with sm. str.

Teichmüller space: $\text{Teich}(X)$

$\{ \mathbb{C}\text{-str on } X \} / \sim$

where $J \sim J'$ if \exists diffeo φ isotopic to id $J = \varphi^* J'$.

moduli sp. of \mathbb{C} -str: $M_{\mathbb{C}\text{-str}}(X)$

$\{ \mathbb{C}\text{-str on } X \} / \sim$

where $J \sim J'$ if $\exists \varphi, J = \varphi^* J'$.

$M_{\mathbb{C}\text{-str}}$ is in general not a variety, but we can study locally.

how can we deform J to get another \mathbb{C} -str J' ?

A deformation of X is a smooth proper map from S with $0 \in S$

$Y \rightarrow S$ s.t. fiber over 0 is $Y_0 = X$.

say Y is a family of \mathbb{C} -mfds parametrized by S .

think of "small perturbation" as family over $S = \text{Spec } \mathbb{C}[x]/(x^2)$.

A universal family $D(X)$ would parametrize all deformations of X where $0 \in D(X)$ is the trivial deformation

so it has a universal deformation

$$X \rightarrow \text{Def}(X),$$

Idea: if $s \in \text{Def}(X)$ is "some defonator X' ", then $Y_s = X'$.

For $Y \rightarrow S$, we have

$$\begin{array}{ccc} Y' & \xrightarrow{\quad} & Y \\ \downarrow & & \downarrow \\ S & \xrightarrow{\quad} & \text{Def}(X). \end{array}$$

Then If $H^0(X, T_X) = 0$ then \exists universal deformation

If S is contractible (say a small disk) then we expect $Y \rightarrow S$ to trivialize

so $Y = X \times S$ and each fiber (Y_s, J) is diffeo to X , say $\varphi_s: X \cong Y_s$ by and φ_s is continuous in s , so $X' = (X, \varphi_s^* J)$ is a "deformed" \mathbb{C} -str.

How do we "measure" the deformation?

The idea is to measure how much the complex gradt changed.

We have $T_X = T_X^{1,0} \oplus T_X^{0,1}$ decomposed into z and \bar{z} parts
 $\Omega_X = \Omega_X^{1,0} \oplus \Omega_X^{0,1}$.

As J vary continuously the $(1,0)$ forms also vary continuously.

if X' is close to X , and then

$$\pi_X^{1,0}|_{\Omega_X^{1,0}}: \Omega_X^{1,0} \rightarrow \Omega_X^{1,0}$$

is an isomorphism.

The difference between J and J' is then

$$s: \Omega_X^{1,0} \rightarrow \Omega_X^{0,1}$$

$$s = -\pi_X^{0,1} \circ (\pi_X^{1,0}|_{\Omega_X^{1,0}})^{-1}$$

the image of s is $\pi_X^{0,1}(\Omega_X^{1,0})$.

so when $X = X'$, $s = 0$.

Conversely, a small map $s \in \Gamma(X, T_X^{1,0} \oplus \Omega_X^{0,1})$ induces an dn. \mathbb{C} -str.

Let $\Omega_{X'}^{1,0}$ be the graph of s . $\Omega_{X'}^{0,1}$ is the J -conjugate of $\Omega_X^{1,0}$.

Then the decomposition $T_x^{1,0} \oplus \Omega_x^{0,1}$ gives J' .

How to tell if J' is integrable?

$T_x^{1,0} \otimes \Omega_x^{0,*}$ has a Lie bracket

$$[\alpha \otimes d\bar{z}_I, \alpha' \otimes d\bar{z}_J] = [\alpha, \alpha'] \otimes (d\bar{z}_I \wedge d\bar{z}_J)$$

and differential $\bar{\partial}$ acting by $\Omega_x^{0,*} \rightarrow \Omega_x^{0,*+1}$

(differential graded Lie algebra)

Prop J' is integrable iff $\delta s + \frac{1}{2}[s, s] = 0$.

Rank Recall Cauchy-Riemann is $\bar{\partial}f = 0$.

A holomorphic w.r.t J' satisfies $\bar{\partial}f + s \cdot \bar{\partial}f = 0$. ($\delta_{J'} f = 0$)

Consider a curve $(-\varepsilon, \varepsilon) \rightarrow \text{Diff}(X)$

(*) this corresponds to $s(t)$ s.t. $\bar{\partial}s(t) + \frac{1}{2}[s(t), s(t)] = 0$, $s(0) = 0$.

so $s'(0)$ is a "tangent vector of $\text{Diff}(X)$ ".

To get the tangent of Teichmüller space, we need to divide by $\text{Diff}(X)_0$.

The action by $\text{Diff}(X)_0$ on C^{∞} is the same as the action of a family

$v(t) \in \Gamma(X, T_x^{1,0})$ with flow $\varphi_t : X \rightarrow X$, $\varphi_0 = \text{id}$.

Expand s as a power series $s = \sum s_i t^i$, $s_i \in \Gamma(X, T_x^{1,0} \otimes \Omega_x^{0,1})$

why the condition (*) what do we know about s_i ?

(*) mod t^2 gives $\bar{\partial}s_i = 0$, but we still need to mod out $\text{Diff}(X)_0$

Write $s = \sum s_{ij} dz_i \otimes d\bar{z}_j$ locally, so

$$dz_i - s(dz_i) = dz_i - \sum s_{ij} t d\bar{z}_j + O(t^2)$$

Write $v(t) = \sum f_i dz_i$ then $\varphi_t(z_i) = z_i + t f_i + O(t^2)$

$$\therefore \varphi_t(dz_i - s(dz_i)) = dz_i + t \left(\sum (-s_{ij} + \frac{\partial f_i}{\partial z_j}) d\bar{z}_j \right) + t \sum \frac{\partial f_i}{\partial z_j} dz_j + O(t^2).$$

These are $(1,0)$ -forms of X' , spanning

$$dz_i - t \left(\sum \left(s_{i,j} - \underbrace{\frac{\partial f_i}{\partial z_j}}_{\bar{\partial} v} \right) dz_j \right) \quad \text{as } f_i \text{ vary}$$

Hence s_i can take values in

$$\begin{aligned} "Def_1(X)" &= \ker(\bar{\partial}: \Omega^{0,1}(T_X^{1,0}) \rightarrow \Omega^{0,2}(T_X^{1,0})) \\ &= D_X(C^\infty(T_X^{1,0})) \quad \text{Im}(\bar{\partial}: C^\infty(T_X^{1,0}) \rightarrow \Omega^{0,1}(T_X^{1,0})) \\ &= H^1_{\text{ Dolbeault}}(X, \Theta_X) \quad \text{first order infinitesimal deformation} \end{aligned}$$

This gives a map $T_0 S \rightarrow H^1_{\text{ Dolbeault}}(X, \Theta_X)$ Kodaira-Spencer map.

An explanation (X, J) is given by charts U_i , and holomorphic fun φ_{ij}
 perturbing φ_{ij} yields v.f. v_{ij} satisfying Čech-cocycle condition
 mod out bds $\varphi_i: U_i \xrightarrow{\sim} U_i$ is modding out Čech coboundary.
 so also get $H^1(X, \Theta_X)$

Let A Artin local C -alg e.g. $C[[t]]/(t^2)$. with unique maximal ideal m_A .

$$\text{let } D_X(A) = \frac{\{s \in T(X, T_X^{1,0} \otimes \Omega_X^{0,1}) \otimes m_A \mid \bar{\partial}s + \frac{1}{2}[s, s] = 0\}}{T(X, T_X^{1,0}) \otimes m_A}$$

$s \in D_X(A)$ corresponds to $Y_A \rightarrow \text{Spec } A$ (inf def of C-sys over A).

But what about converse, given s_i is there $s(t)$ with $s'(0) = s_i$?

$$\bar{\partial}s(t) + \frac{1}{2}[s(t), s(t)] = 0 \implies \bar{\partial}s_2 + \frac{1}{2}[s_1, s_1] = 0, \bar{\partial}s_3 + \dots$$

so $[s_1, s_1] \in \text{Im } \bar{\partial}$. Recall $[s_1, s_1] \in \ker \bar{\partial}$ (wedge of closed form is closed)

so s exists only if $[s_1, s_1] = 0$ in $H^2(X, T_X)$

This is the primary obstruction to s .

If $[s_1, s_1] = 0$, then the next obs is $[s_1, s_2] \in H^2(X, T_X)$, etc.

If $H^2(X, T_X) = 0$ then there is no obstruction, and s always extends.

But this is not true for CY mod,

so the following is surprising.

T^m (Bogomolov - Tian - Todorov) true if $H^1(X, \mathcal{O}_X) = 0$.

X cpt C.Y with $H^0(X, TX) = 0$ (automorphisms are discrete)

$\text{Teich}(X)$ is smooth near X with tangent $H^1(X, TX)$. (no obs)

$M_{\text{ex}}(X)$ is an orbifold near X with tangent $H^1(X, TX)$.

Proof of no obs is by showing an element $D_X(A_n)$ lifts to $D_X(A_{\text{obs.}})$

for $A_n = \mathbb{C}[[t]]/(t^n)$.

Cech argument can show this lifts only if an obs class in $H^2(X, \mathbb{Z})$ vanishes.

Kahler deformations

- the space of Kahler forms $[\omega] \in H^{1,1}(X)$ form open convex cone.
- Deformations are constrained by Hodge symmetry.
- X and mirror \tilde{X} have mirror map

\mathbb{C} -moduli of $X \leftrightarrow$ Kahler moduli of \tilde{X} .